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Non-Pick Control Contro Control Control <t< td=""><td>6 Mean Pelvic Tilt</td><td>15.92518</td><td>9.3013</td><td>6.623884</td><td></td><td></td><td>γ4 C</td><td>1.263431</td><td>2.</td><td>4</td><td>5.360613</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></t<>	6 Mean Pelvic Tilt	15.92518	9.3013	6.623884			γ4 C	1.263431	2.	4	5.360613								
0 10 <t< td=""><td>B Mean Pebic Rotation</td><td>0.048943</td><td>4.1077</td><td>0.405143</td><td></td><td></td><td>yo x6</td><td>-0.6376</td><td>79</td><td>5</td><td>-3 22436</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></t<>	B Mean Pebic Rotation	0.048943	4.1077	0.405143			yo x6	-0.6376	79	5	-3 22436								
B (MA (F) Peter and (F) 20134 (F) 2017 (F) 20135 (F) 2017 (F) 20135 (F) 2017 (F) 201	9 Min Hip Flex-Ext	-4.96981	-8.8449	3.875093			ý7	-0.42066	zi	7	-2.37397								
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••••••••••••••••••••••••••••••••••••	1 Peak Hip Add in swing	-5.49128	-2.5103	-2.98098			y9	-1.5056	Z	3	-6.11799								
Thing of the log of the state is a state is	2 Mean Floy IC	7.832569	7.5269	0.305659			yiu v11	-0.11622	2	11	1.802063								
6 MCM complexity 2000 9989 37320 110 4.0527 111 49.0437 6 MCM complexity 8 000 3.050 116 3.0620 113 3.0637 8 MCM complexity 8 000 3.050 116 3.0620 113 3.0637 8 MCM complexity 8 007 3.050 114 3.0620 113 3.0637 8 MCM complexity 8 007 3.050 114 3.0620 113 3.0637 9 MCM complexity 8 007 3.050 116 3.0637 3.051 9 MCM complexity 8 007 3.050 116 3.0517 9 MCM complexity 1007 1000 3.0517 116 3.0517 9 MCM complexity 123 10 10 10 10 10 10 10 9 MCM complexity 123 10 10 10 10 10 10 10 10 10 10 10 10 10 10 10 10	4 Timing of Max Knee Flex	74	70.6389	3.3611			y12	4.488902	2	12	9.595477								
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